The critical frequency, \( f_{\text{crit}} \), for the filters that will be designed is the \(-3\) dB frequency for the low-pass and high-pass filters, pole and/or zero for the shelving filters, and the center frequency for the all-pass filter. The critical frequency is the experimenter’s birthday (sans year) in kHz for birthdays prior to July and the birthday divided by two for birthdays from July to December. For instance, if the experimenter was born on May 24 the critical frequency is 5.24 kHz and if the experimenter was born on December 13 the critical frequency is 12.13/2 = 6.065 kHz.

1. Design a first order low-pass filter with a dc gain of \( 20\delta B \) and a \(-3\) dB frequency of \( f_3 = f_{\text{crit}} \).
2. Design a first order high-pass filter with an infinite frequency gain of \( 20\delta B \) and a \(-3\) dB frequency of \( f_3 = f_{\text{crit}} \).
3. Design a first-order low-pass shelving filter with a pole frequency of \( f_p = f_{\text{crit}} \), a dc gain of \( 20\delta B \), and an infinite frequency gain of \( 6\delta B \).
4. Design a first-order high-pass shelving filter with a zero frequency of \( f_z = f_{\text{crit}} \), a dc gain of \( 6\delta B \), and an infinite frequency gain of \( 20\delta B \).
5. Design a first-order all pass filter with a phase shift of \( 90^\circ \) at \( f_0 = f_{\text{crit}} \).

Simulate each of the circuits designed above with both National Instruments (Multisim) and LTSpice. Plot the Bode plots from a frequency a decade below the smallest pole/zero frequency to a decade above the pole/zero frequency. Make the same plots with both Mathcad and Matlab.

Each of these filters will be built in lab and the frequency response obtained. For the first four filters only the amplitude response is required to be measured in lab. But for the all pass filter both amplitude and phase must be measured; ELVIS might be the preferred choice for this filter.